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### PHASE I SMALL BUSINESS INNOVATION RESEARCH (SBIR) PROGRAM

Proposal No: A012-0770 Topic No: A01-166 Start Date: 1/31/2002 Finish Date: 7/31/2002

Firm Name: Micron Instruments

Mail Address: 4509 Runway St, Simi Valley, CA 93063

Principal Investigator: Mr Herb Chelner

### PHASE I FINAL REPORT

PERIOD 1/31/2002 TO 7/31/2002

# EMBEDDED SENSOR TECHNOLOGY FOR SOLID ROCKET MOTOR HEALTH MONITORING

**MICRON REPORT NO: 02-221A** 

#### **ABSTRACT**

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### SECTION 1 - Program Milestones and Deliverables

The SBIR Phase I kickoff meeting took place at the Propulsion and Structures Directorate of the U.S. Army Aviation and Missile Command (AMCOM) on the 14<sup>th</sup> March 2002. Representatives from MICRON, DASCOR, and AMCOM Propulsion and Structures and Engineering Directorates were in attendance. MICRON Instruments personnel presented their planned approach to achieving the goals set forth in the Department of Defense FY 2001 Program Solicitation 2001.2. The Phase I Objectives listed in the solicitation were as follows:

### Phase I Objectives:

- Perform literature review, development, and investigation to select one or two most promising sensor technologies to be used as an embedded sensor for monitoring stress and/or strain in solid rocket motor bondlines.
- Fabrication of 12 selected sensors and 3 loggers with associated calibration sheets.
- Design and manufacture of equipment to precision match the semiconductor stress sensing elements for future production of improved sensors.
- Establish temperature and pressure sensitivity, long-term measurement stability and chemical compatibility, and in the field sensor calibration procedures.
- Develop associated prognostics (i.e. what does the sensor reading mean w/r/t solid rocket motor structural and ballistic integrity).
- Consider the requirements to establish integration into RRAPDS system (provide capability for continual or intermittent monitoring of sensor readings through RRAPDS or a data acquisition scheme compatible with RRAPDS).

Through the results of literature review (discussed in section 2) and past sensor development (funded largely by Micron Instruments and other NATO countries), it was shown that an imbedded stress transducer would meet the majority of the desired features and would provide data addressing the most critical, and yet most difficult parameter for evaluation in a solid rocket motor health monitoring system – transient bondline stress. Sensor features such as operational temperature range, accuracy, sensitivity, non-intrusiveness, long term measurement stability, versatility, robustness for installation, safety, low power requirements, ease of calibration, material compatibility, low corrosion sensitivity, and cost were all given consideration. A cooperative laboratory study was conceived with AMCOM personnel, to obtain valuable data focused upon achieving the Phase I objectives.

The first batch of six sensors and two data loggers were delivered for installation into laboratory analogs and the required training session to use the associated data logger software has been successfully completed.

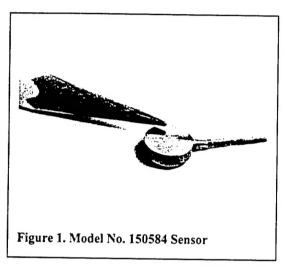
The following sensors were delivered in batch one: Model No. #150584 (as shown in Figure 1) and the calibration sheets are given in Appendix A for reference.

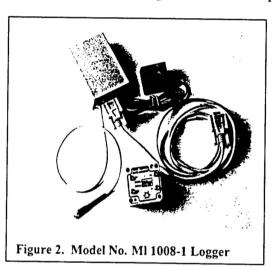
Serial No	Sensitivity (mV)	Static Error Band (%FS)
60716	18.83	0.176
60717	21.48	0.236
60718	21.86	0.093
60719	19.30	0.078
60720	20.46	0.225
60721	21.06	0.081

The following data loggers were also delivered: Model No Ml 1008-1 (shown in Figure 2) and the calibration sheets are given in Appendix B for reference.

Serial No.	$V_{offset}$ (V)	Gain
9823-0006	2.04/1.02	158.5/19.81
0107-0004	2.04/1.32	153.3/19.43

The given values are the average of the four stress channels/average of the four temperature channels.





A second batch of sensors and a high frequency logger have been delivered for further testing. The calibration sheets are given in Appendix A for reference.

Serial No.	Sensitivity (mV)	Static Error Band (%FS)
62176	20.88	0.1754
62177	22.26	0.3244
62178	21.51	0.3602
62179	35.29	0.2358
62180	18.16	0.0874
62181	24.29	0.1782
	>	0.1/02

A High Frequency logger Model No ML1001-8-1HF was also delivered and the calibration sheet is also given in Appendix B for reference.

Serial No.	$V_{\text{offset}}$ (mV)	Gain		
0207-0001	2496.46	5.011/74.326		

### SECTION 2 - Review of Sensor Technology

A critical review of published papers (a list is given in Appendix C) has been undertaken. The reported results from trials using Micron embedded sensors have been assessed to establish the achieved performance of the technology. The results can be characterized into two separate areas: Sensor Performance and Installation Effects.

#### 2.1 Sensor Performance

The majority of sensors performed as calibrated with properties as reported on the associated calibration sheets. A reliability problem with the robustness of the plug/socket used to attach the sensor cable to the bridge completion unit and to the logger was responsible for intermittent continuity. This problem has been addressed and more robust electrical connectors will be used for Phase II sensors.

A requirement to seal the sensor to ambient pressure was also established when high-pressure calibration trials were undertaken on 'bare' sensors and a number of the units leaked and equilibrated to zero load. To overcome this problem it has been recommended that a scheme be developed to hermetically seal the sensor as part of the Phase II submission. This would also improve the sensor stability and long term accuracy. Work will been performed at AMCOM using the supplied sensors to establish temperature and pressure sensitivity over the temperature range -50°F to +150°F and pressures up to 100 psi. The pressure sensitivity results will be discussed later in this report.

### 2.2 Installation Effects

It is essential that the sensor be correctly mounted in the test sample. To make the most accurate stress measurement, the mounting should be as non-compliant as possible (i.e. rigid with respect to the propellant grain). However, the optimal method of installation will depend upon the particular design and manufacturing sequence of the solid rocket motor, its own structural and thermal requirements, and the location in the motor for which the stress is to be measured. One objective of the design of the laboratory analog was to address whether the effect of installation into a semi-rigid insulation could be tolerated and whether the effect of insulation compliance could be compensated for within the sensor calibration. In this way, more options may be provided to the motor manufacturer to achieve compromise between the needs of the motor, the required manufacturing operations, and proper sensor installation.

A second requirement for accurate stress measurement is that the propellant must be well bonded to the sensor or through its various interfaces. Cleanliness is essential to facilitate good bonding. Long term chemical compatibility of all, the components must also be assured for both safety and structural integrity. In the laboratory analog design chosen for Phase I, the sensor has been installed at the interface between the liner and insulation. The liner material is approximately 0.020 inches thick, and is composed of the same polymeric base material as the propellant (hydroxyl terminated polybutadiene). Pathfinder analogs were cast and liner peel testing was completed to ensure that liner formulation and cure were adequate to achieve a good bond to the surface of the sensor. Each rocket motor/laboratory analog sample geometry can be different with unique problems for egress and cable management with respect to installation. Past experience and recommended practice has been documented. Methods of cable management and egress from a tactical motor will be developed and tested as part of the Phase II work items.

## SECTION 3 - Precision Semiconductor Strain Gage Matching System (PMS)

## 3.1 Typical Thermal Gage Matching Systems and Limitations

Manufacturers of semiconductor gages sell their gages in thermally matched sets of two or four. Unlike foil or wire gages, the semiconductor gage has a very large change in resistance with temperature. If not thermally matched for slope and intercept, temperature compensation for balance would be difficult and over all performance would be compromised.

Gages are normally installed (soldered) free standing so that induced stress is minimized. The circuit board is designed to go into a temperature chamber. Air that is heated or cooled enters the chamber from one side and exits at the opposite side. Small temperature chambers are used to minimize the thermal differential across the chamber, which determines the resistance tolerance in the gage matching. Approximately fifty gages are installed onto a circuit board and four boards are inserted and form a three dimensional array in the center of the chamber. The object is to minimize the thermal differential across the chamber and the new system has been designed to eliminate these uncertainties.

To read the gage resistance, power is applied from a constant current supply and the circuit compensates for any line change. A computer measures the gage resistance taking multiple readings over a finite period of time and averages them. This is done to reduce noise error and increase the accuracy. Resistive readings are taken at -50, 0, 78 and 278 °F. The gage sets are matched within plus or minus two ohms. Due to the thermal differentials across the three dimensional array of circuit boards, thermal resistive errors of up to +/- four percent of the ambient resistance is possible. These resistive errors increase the thermal non-linearity and decrease the long-term stability when used in bridges for sensor application.

### 3.2 PMS Description and Hardware

A new test panel has been designed to support the Precision Semiconductor Strain Gage Matching System (PMS) program. Two have been produced to support testing of up to four gage boards in the temperature chamber. Each test panel contains four relay select boards and an interconnect board. Test current is programmable by using the Sentinel's analog output capability. The test arrangement is shown in Figure 3.

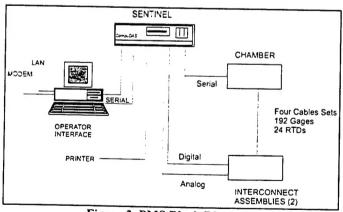


Figure 3 PMS Block Diagram

A new gage test board has also been developed. This gage board arranges gages in a series arrangement in groups of 12. Four sections on the board provide for 48 gages. Four boards are loaded into a temperature chamber of size and operation used in the presently used standard matching system. A populated board is shown in Figure 4. The gages resistance is measured by exciting the gage with constant current to cancel any

line resistance changes and measuring the voltage drop across the gage with is proportional to resistance. The PMS measures the actual temperature across the three dimensional array of gages on the circuit boards.

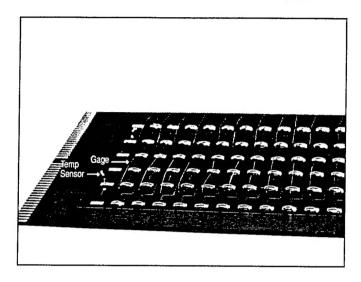


Figure 4. PMS Populated Gage Board

### 3.3 PMS Operation

One "Quad", or group of 12 gages, is selected. A test current is passed through the string plus three additional series elements. Two elements are platinum RTDs, which are mounted on the gage test board, one at each end of the 12 gages. The third element is a precision shunt mounted in the test panel. All 15 devices (12 gages, 1 shunt, and 2 RTDs) have the identical current flowing through them. The Sentinel measuring and control system reads the 15 voltages in a high-speed mode. Each device is read 17 times over a 60 cycle time period so that a 60 Hz digital filter can be applied. The 15 devices are read in a total elapsed time of 180 milliseconds. The RTDs are used to map the temperature of each gage. Using this data it calculates the true temperature at the gage location being measured. With this data, the system calculates the difference in temperature at the gage location and the specified true test temperature. The resistance of the gage, if it was at the test temperature, is calculated and used to match the gages. Accuracy of measurement more than ten fold better than the standard system will be possible.

### 3.4 Accuracy of system

The Sentinel system uses a 16 bit ADC and is calibrated to 0.01%. Application software has been created that features an auto zero correction for each of the 15 analog input channels. Test current is measured and known for each Quad test. The end result of this design is measurement accuracy and repeatability of 0.1 ohms with nominal 500 ohms gages. Test data taken from a reference test board is shown in Appendix D. Precision known resisters were used for this board to eliminate the effects of temperature or time variations for the measurement of system stability and accuracy. Channels 0 and 13 are the locations for the RTDs. Channel 14 is the system shunt. Channels 1 through 12 are the gage assignments. The elements on this board were measured with a 6 digit HP ohmmeter using the four wire measurement technique. Three sets of actual readings are presented to demonstrate repeatability. Actual sample values are presented with the first group of readings and as can be seen the difference is less than 0.015%. The measurement accuracy is better than 0.2 ohms which is a twenty fold improvement. This precision gage matching is expected to permit production of sensors with minimum long-term drift.

Well designed motors using established propellants with well know characteristics and which are not pushing the technology are expected to last 15 years or more. The error due to long term drift of health monitoring sensors must be within the allowable error band, which could be as low as one psi for such motors. If the drift is low and predictable, the data can be corrected and the accuracy required achieved.

## SECTION 4 - Long Term Measurement Stability

Calibration checks of the sensor after casting of the propellant grain is not possible, therefore it is essential that the units used for long term health monitoring are accurate and stable. Any creep or zero shift in the sensor output would be indistinguishable from changes in the measured bond stress. Long term changes in balance with no sensor stress have also been run and were found to be acceptable. To test the stress stability of the current system a cantilever constant load test consisting of a static load applied to the sensor diaphragm was initiated and has been running for 28 weeks. The loading fixture is shown in Figure 5 and a local view of the sensor under tension load shown in Figure 6. The stress was applied to the sensor via a hard rubber interface and hanging weights. Extra care was used to ensure that the bonded surface area was limited to be that of the active surface area of the sensor diaphragm. The test rig was exposed to the ambient temperature variations and the data downloaded at regular intervals. An outline of the results for the test is given below with the start and end values for each download period.

Date	Start(V)	Finish (V)
31 <sup>st</sup> December	2.410/1.593	2.395/1.598
31 <sup>st</sup> Dec to 22 <sup>nd</sup> Jan	2.395/1.616	2.416/1.703
22 <sup>nd</sup> Jan to 19 <sup>th</sup> Feb	2.417/1.721	2.415/1.720
20 <sup>th</sup> Feb to 24th April	2.411/1.717	2.435/1.725
2 <sup>nd</sup> May to 16 <sup>th</sup> July	2.437/1.735	2.445/1.833



Figure 5. Test Rig

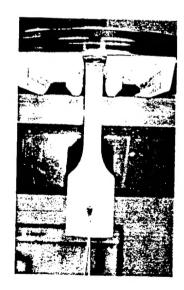


Figure 6. Sensor under Test

The plot of the results are given in Figure 7 which shows that the variation of output is  $2.42 \pm 0.025$  V for the load which is limited by the accuracy of the logger, and the ambient temperature variations. The trend of the load follows the average increase in the ambient temperature. There is no significant indication of sensor creep, i.e. a reduction in the recorded load, in the results for the test period of 28 weeks and the test will continue until the end of the year.

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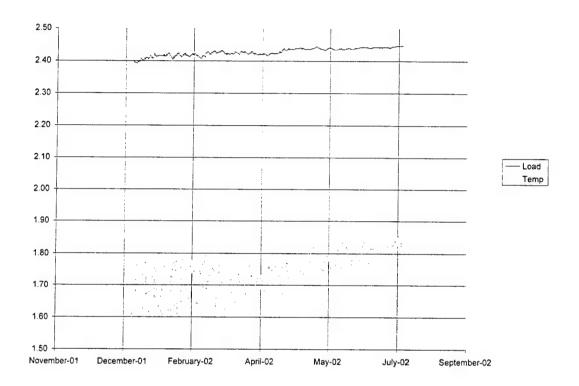


Figure 7. Long Term Stability Test Results

### SECTION 5 - Evaluation of Chemical Compatibility

One of the concerns which must be addressed for any embedded sensor in a solid rocket motor is whether the sensor itself is compatible with the chemistry of the propellant, the liner, and the insulation in the bondline. Of these, the propellant will contain the most caustic constituents.

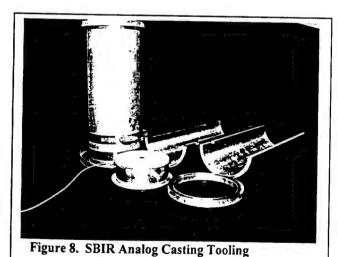
In typical solid rocket motor applications, there will be one of two common families of materials which must be considered; and these are associated with the type of propellant system used in the rocket motor. The two types of systems can be generally described as either composite or double base propellants. In the former, the propellant is composed of rigid oxidizer and fuel particles embedded in an inert polymeric matrix (approximately 84-91% solids by weight). In the latter, the propellant is composed of nearly all polymeric material, some of which may be energetic, and may also contain some level of solids loading. Composite propellants normally use ammonium perchlorate or ammonium nitrate as their oxidizing agents; both are materials which can go into solution and produce corrosive by-products in the presence of significant moisture. Double base propellants, by comparison, can contain many types of chemical explosives, such as nitroglycerin. Both families can contain trace elements such as plasticizing agents, ballistic modifiers, and stabilizers; which are subject to diffusion processes, and which may in fact have long term effects on sensors installed in motors.

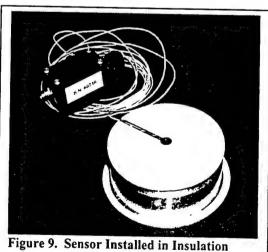
An exhaustive evaluation of this issue could not be addressed within the scope of a Phase I effort. Fortunately the double base propellant motors, due to the high strain capability of their formulations, are much less susceptible to bondline stress failures (their aging mechanism is more governed by loss of chemical stabilizer through depletion reactions). For this reason, a composite propellant formulation was chosen to be used in the laboratory studies (HTPB/AP/AL).

An evaluation of sensor construction and materials can be used to infer the inherent chemical compatibility and resistance to corrosion. The sensor main cavity is composed of either 6Al-4V titanium or 17-4 precipitation hardened stainless steel. Both materials are relatively impervious to attack from hydrochloric or nitric acids; one by-product of ammonium perchlorate or ammonium nitrates in solution. The lead wire exiting the sensor is covered with a 0.010 inch thick, Teflon insulation, which is also not expected to be in any measurable way affected by propellant constituents. While this version of the sensor is not hermetically sealed, any significant moisture penetration into the sensor cavity is not expected; and would result in far worse damage to the motor itself, than to the embedded sensor.

### **SECTION 6 - Sensor Calibration Procedure**

As discussed in previous sections, a particular laboratory analog geometry, propellant material, and construction approach was selected, to be consistent with the objectives of the Phase I study, and to provide laboratory test articles for use by AMCOM. Despite the fact that the most accurate installation of the sensor would be placement directly onto the metal substrate (motor case or bond tab), it was of equal importance that other installation methods be assessed. Previous investigations, described in the literature, had not fully characterized the tolerance to and the effects of, insulation compliance. For these reasons, and to achieve simplicity in casting tooling design, AMCOM personnel chose to install sensors into the insulation substrate which made up the structure of the bondline. The insulation material was Kevlar-filled PolyIsoprene; for which cure, stiffness, and adherence properties were assessed in separate studies. The analog casting tooling and sensor installation are shown in Figures 8 and 9, respectively. The insulation was machined to contain a small cavity and slot in which the sensor could be embedded and bonded in place with epoxy (FUSOR 305, Lord Chemical). This installation method ensured that the sensing diaphragm would be located precisely at the insulation-to-liner interface.





Selecting this method of installation, while most convenient for analog casting, also meant that considerable effort must be expended to perform calibrations of the sensors which accounted for insulation compliance. To achieve this, a series of tools were fabricated. MICRON sent to AMCOM a factory calibration fixture, to

calibrate the sensors using dry nitrogen gas pressure (0 to 100 psi). An additional calibration chamber was fabricated, so that the same sensors could be re-calibrated after being installed into the insulation on the end tab. In this way, the effect of insulation compliance could be measured and accounted for in data reduction for combined loads testing of the analogs. Shown in Figure 10 are the calibration station and test fixtures.

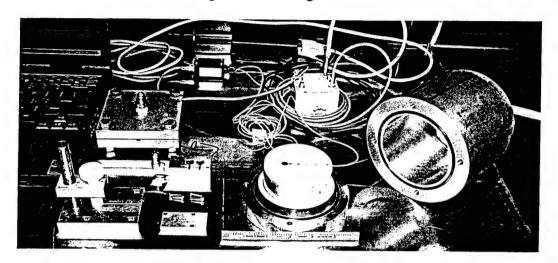


Figure 10. Sensor Calibration for Insulation Compliance

Shown in Figures 11a and 11b is a comparison of calibration curves for sensors #60718 and #60719, which show that the factory calibration fixture and AMCOM calibration fixture both provide similar data, and that when embedded in the insulation, the effects of compliance may either increase or diminish with pressure. The reason for this phenomenon is not clearly understood and more evaluation of this issue is needed. Nonetheless, the results thus far give good confidence that the effect of insulation compliance may be accounted for on a case-by-case basis, prior to propellant casting.

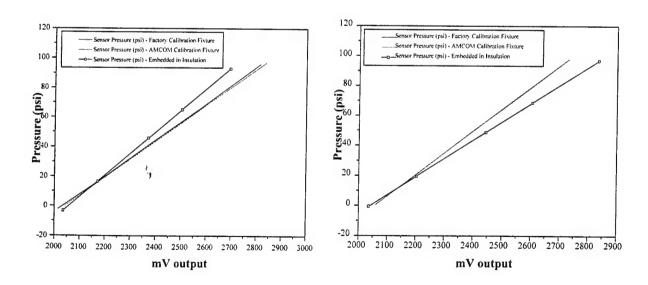


Figure 11a. and 11b. Respective Calibration Curves, Accounting for Insulation Compliance

## **SECTION 7 – Development of Associated Prognostics**

AMCOM personnel conceived and implemented a series of tests using the cast laboratory analogs. The first six tests of the series have recently been successfully completed, and are reported herein. The concept for the testing was to devise a laboratory test article, which would be subjected to combined loads and cyclic testing, with known and controlled boundary conditions, while simultaneously measuring global loads and displacements. In this way, the articles might be subjected to realistic and complex loading scenarios and the embedded sensors might be rigorously challenged for accuracy and sensitivity. The testing took place with specimens oriented at angles ranging from 0° (pure tension) to 90° (simple shear). Through finite element analysis of the analog geometry when subject to asymmetric loads, the stress distribution and its expected magnitude at the bondline are known. The combination of measurement of global loads and displacements, along with stress analysis provides means to validate sensor performance.

### 7.1 Laboratory Analog Stress Analysis

Prior to installation of sensors into the analogs, a series of two and three dimensional finite element analyses were performed. The viscoelastic materials were treated as linear elastic, nearly incompressible. The objectives of these analyses were:

To size the laboratory analog specimen

To investigate its interior stress distribution

To identify and mitigate stress concentrations at remote boundaries

To evaluate the sensitivity of the bondline arising from a rigid embedded sensor

To investigate sensitivity of the geometry to various ratios of propellant to insulation stiffness;  $\mathbf{E}_{\mathbf{p}}/\mathbf{E}_{\mathbf{l}}$ .

Shown in Figure 12 is one such finite element model, and a plot of the stress at the interface. A discontinuity exists due to the sensor on the insulation side which is not mirrored on the propellant side. The discontinuity was independent of propellant and insulation stiffness within the range selected ( $1 \le E_P/E_1 \le 10$ ). The 2D model also allowed investigators to optimize overall aspect ratio (height-to-diameter). Once the two-dimensional axisymmetric analyses were completed a three-dimensional model was developed, and used to assess the stress distribution in the analog when subject to asymmetric loading (tensile, combined tensile-shear, simple shear). Shown in Figure 13 are the deformed geometry for each configuration and a concurrent plot of the stress distribution along the bondline interface. A stress relief groove cut into the insulation was determined to be needed to reduce (but not eliminate) the stress concentration around the perimeter of the specimen. The finite element analysis also showed that the maximum stresses for each loading condition did not occur in the geometric center of the specimen. For this reason, some of the analogs were fabricated with the sensor offset by one third of the bonded diameter, and combined loads testing completed for comparison to those with sensors in the center. Overall the finite element analysis showed that the analog was suitable to meet the objectives for which it was designed.

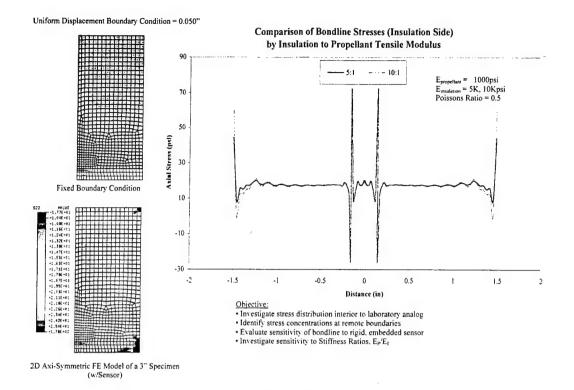


Figure 12. Two Dimensional Finite Element Model of Laboratory Analog

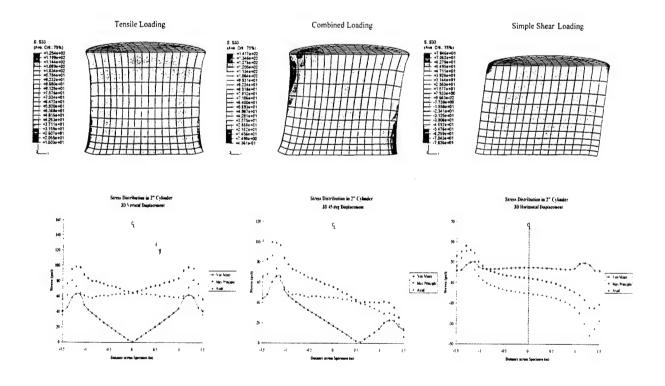


Figure 13. Three Dimensional Finite Element Models of Laboratory Analog

### 7.2 Analog Fabrication

Analogs were cast and cured by AMCOM personnel. After bonding the insulation in place onto an end tab, the insulation is machined, the sensor bonded, and a 24-hour cure cycle (+140°F) imposed to dry out the insulation and fully cure the epoxy. Liner is mixed, manually applied by brush, and pre-cured for 24 hours. Prior to assembly into the casting tooling, a thin "wet coat" of liner was applied, to ensure the best propellant-to-liner bond. Propellant is mixed and vacuum cast, and the analogs are cured for six (6) days at +140°F. Following removal from the curing oven and a 24-hour cool down period, the analogs are de-tooled and prepared for testing by machining the upper surface and bonding an endtab.

The configuration of the analog is shown schematically in Figure 14. It may be seen that the test geometry is a right circular cylinder, with a height to diameter ratio of approximately 1. This design, when tested in combined loads or cyclic tension, produces a stress state at the bondline, which is highly constrained and multi-axial; similar to that in a rocket motor. However, one advantage is that unlike a rocket motor, stresses may be induced mechanically (in a tensile test machine), rather than thermally; thus negating the complexity of specifically treating the thermo-viscoelastic material behavior. One modification was made to the specimen that is not shown in the schematic. After stress analysis, it was determined that large stress concentrations existed at the exterior circumference of the specimen, at the bondline interface. To reduce the magnitude of these, a circumferential stress relief slot (0.30 inch depth) was cut into the insulation, as will be illustrated in later figures.

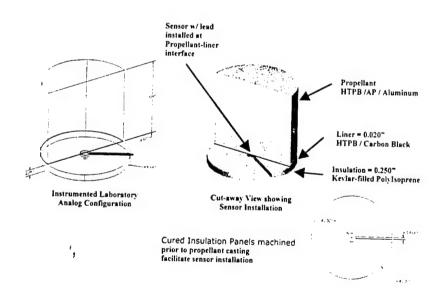


Figure 14. SBIR Analog Configuration Drawing (sans Stress Relief Groove)

The sequence of fabrication steps for an analog are illustrated in Figure 15, which also demonstrates that much of the process requires tactile contact and could lead to some variation in final product. In order to assess any potential for this, a certain amount of the propellant from each casting was cured separately for quality assurance testing of mechanical properties. Also, liner "peel boat" witness samples were cast and tested to verify liner cure and bond quality. This data is shown in Table I.

Table I. Analog Propellant Properties Summary

Mix #	Max Strength (psi)	ε @ Max Load (%)	Initial Modulus (psi)	Break ε (%)	Peel Strength (lbs/in)
GM02-05	119.3	37.7	1053	39.81	Wet = 9.8 No Wet = 7.5
GM02-11	117.2	39.5	1035	41.97	Wet = 17.7 No Wet = 11.1
GM02-21	110.0	38.9	962	42.28	Wet = 13.9
GM02-30	117.1	40.5	809	42.50	Wet=17.4

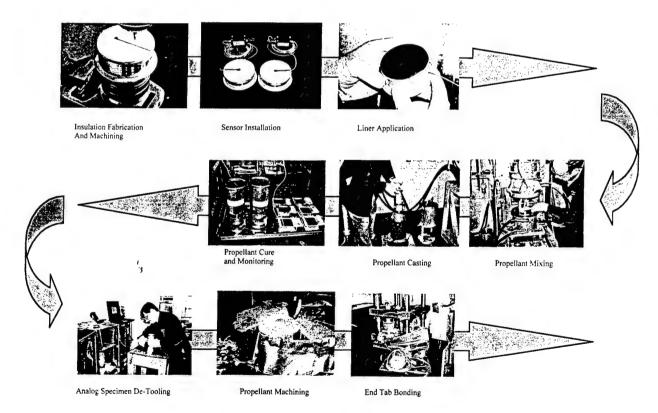


Figure 15. Fabrication Steps for Analog Specimens

During the cure process, post-cure cool down, and de-tooling, embedded sensors were logged to record the build-up of cure stress and any stress induced by de-tooling.

### 7.3 Preliminary Test Results

The first two analogs, designated as #1 and #2, were fabricated with sensor serial numbers #60716 and #60717, respectively. A complex load sequence was implemented, in which each analog was subjected to a series of 5 load cycles, followed by constant strain for 10 minutes (stress relaxation), followed by 5 cycles, followed by constant strain, ... etc. The sequence was repeated in such a way that the strain magnitude in each step was increased 1%, 2%, 3%, etc.; up to failure. The global load and displacement were monitored through computer data acquisition, such that the sensor readings and global measurements could be compared after the test. Analog #1 was subjected to pure tension (0° orientation) and Analog #2 was subjected to a combined tension-shear load sequence (45° orientation). A rigid linear bearing test fixture was fabricated and installed in the INSTRON tensile test machine, to ensure that the boundary conditions would be controlled throughout each test; consistent with those imposed in the finite element stress analysis. The test fixture and Analog #2 are shown in Figure 16 for illustration.

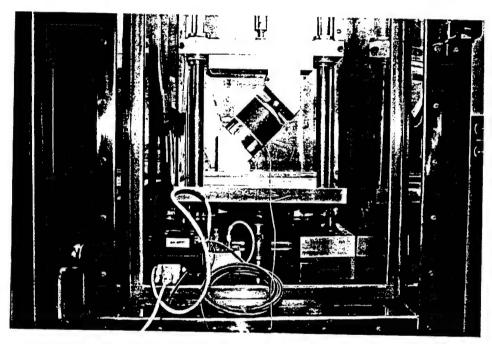


Figure 16. Analog #2 Installed in Rigid Linear Bearing Test Fixture

Test results for Analog #1 and #2 are shown, respectively, in Figures 17 and 18, which also illustrate the complex load sequence. In Figure 17, it is seen that the sensor output follows the nominal stress sequence, defined as the remote load normalized by effective cross-sectional area. More importantly, the sensor captured both the failure event and its location. While the global load still indicates some residual strength capability in the analog, the sensor indicates near-zero stress. Post —test dissection of the article showed that failure had initiated cohesively in the propellant and in close proximity to the bondline.

Similar results are illustrated by Figure 18 for the tension-shear test. Good correlation results between the sensor and global load measurement, up until the initiation of failure. Unfortunately, the analog was installed into the test fixture with the cable exiting the bondline on the tension side. This lead to a premature failure of the sample, remote from the sensor. As can be seen in Figure 19, the failure occurs at the external perimeter rather than interior to the bondline. Figure 19 also illustrates the insulation flap (stress relief) described in previous sections. Still, the sensor correctly records the fact that there is residual capability internal to the analog. This test sequence was repeated with Analog #3, with the cable exiting the sample on the

compression side. An additional improvement to the test was that the sensor was offset from center, closer to the region of maximum shear stress. Comparison of results between tests demonstrates this, as shown in Figure 20.

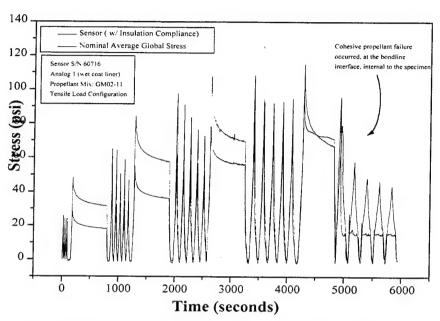


Figure 17. Test Results for Analog #1 (Pure Tension)

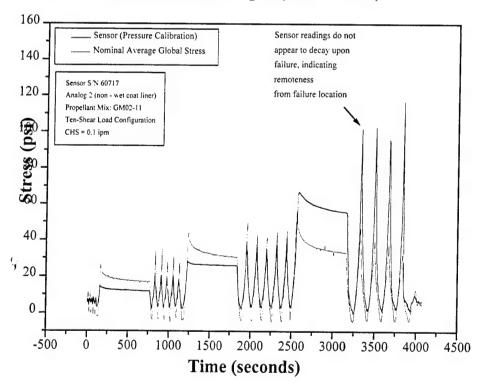


Figure 18. Test Results for Analog #2 (Tension-Shear)

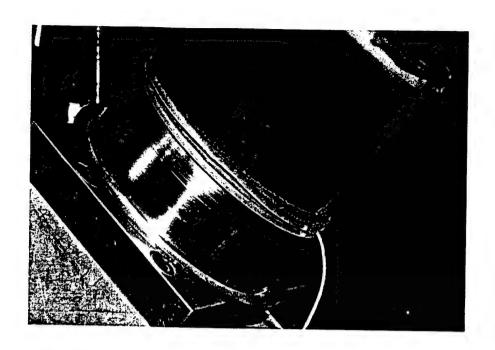


Figure 19. Detailed View of Analog #2 in Tension-Shear

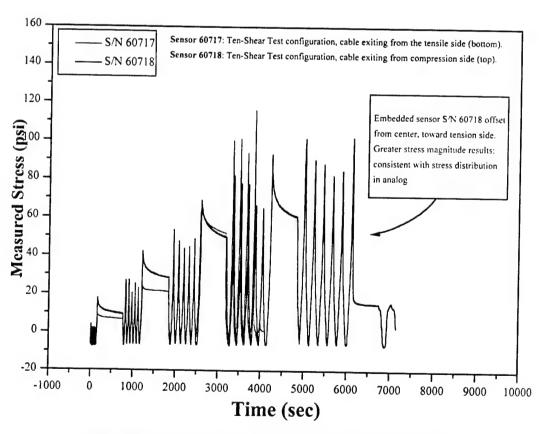


Figure 20. Comparison of Tension-Shear Test Results

Other testing performed with the sensors installed into analogs included cure monitoring and a long-term creep test. Shown in Figure 21 is a plot of the stress history during cure at +140°F. Data from the two sensors exhibits a slight offset (one shows a tensile stress throughout while the other shows tensile stresses only after cooling from cure temperature). Figure 22, shows the apparatus in which Analog #6 was subjected to a constant load creep test, of approximately 100 lbs. (22.5 psi), for greater than 28, 000 minutes. The test results given in Figure 23 shows that the stress begins to rise late in the profile; although data transfer to archive was not consistently achieved. Considerable noise in the signal was induced by the remote power source used for both the data logger and LVDT. These results are indicative of variance of response due to manufacturing and highlight the need for further training, testing, calibration, and analysis.

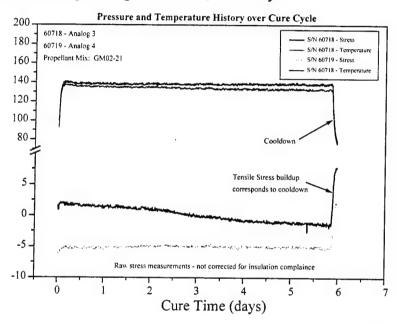
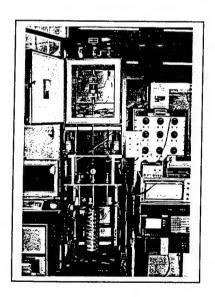


Figure 21. Cure Monitoring of Analogs #3 and #4.



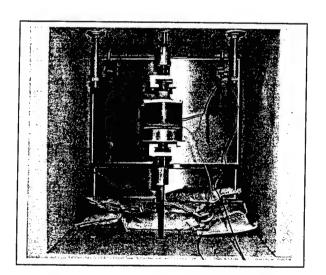


Figure 22. Creep Test Apparatus

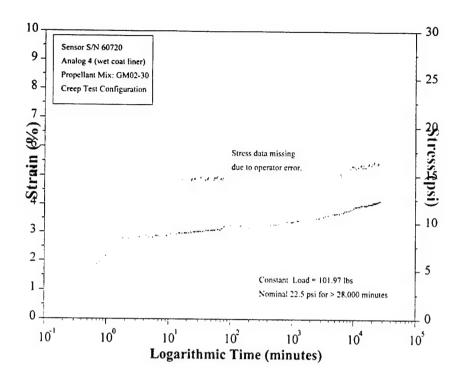


Figure 23. Long Term Creep Test of Analog #6

### **SECTION 8 -Conclusions and Recommendations**

Bondline stress data, continuously monitored, may be directly input into cumulative damage-based failure predictive models or may be used as an instantaneous detector of propellant grain cracks and/or debonds. Optimized placement of stress transducers may even allow triangulation to locate an induced flaw. These features have great benefit and great potential to achieve the ultimate goal of health monitoring in solid rocket motors.

The results of design, calibration studies and functional testing under SBIR contracts provide the Army with confidence that embedded sensors which accurately interrogate and validate structural integrity for rocket motors can be developed and employed with good precision. SBIR Phase II program objectives have been conceived and are being pursued. Of particular interest is to establish installation procedures and combustion chamber egress designs which can be implemented in a rocket motor production environment, to demonstrate these on a production Army motor design, and support data interface and download with prototype RRAPDS hardware.

## APPENDIX A

SENSOR CALIBRATION SHEETS

PRESSUR	PRESSURE TRANSDUCER CALIBRATION DATA							
Model Number	Serial Number	Pressure Range	Type Unit					
150584	60716	100PSI	Gage					
Diaphragm Materials	Customer	Excitation	Excitation Type					
Steel	HUNTSVILLE	4. OnA	Constant Current					

	Pr	essure Cal	Date of Pa	ion 01			
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%PS)
0 PSI G	1.08v	1.08v	1.08=0	1.08mV		0.00008	0.0000
20PSI G	4.83v	4.82v	4.84=	4.85mV	0.0804%	0.05028	
40PSI G	8.6±v	8.57v	8.63=	8.61 <sup>mV</sup>	0.0100%	0.2009	
60PSI G	12.36	12.32v	12.40:	12.38 <sup>mV</sup>	0.0100%	0.3014	0.1005
80PSI G	16.18	16.157	16.14-7	16.14mV	0.1808%	0.15078	0.2009
100PSI G	19.91v		19.98-	19.91mv			0.3516
SENSITIVITY	18.83v	L				L	0.3310

STATIC ERROR BAND

± 0.1758 FS

		Thermal Cal	ibration Dat	a	Date of Thermal Cal	ibration Jun 99
	Low Temp.	Ambient	High Temp	Temperature	Thermal	Thermal
Temperature	-50°F	75°F	150°F	Range	Balance Shift	Sensitivity Shift
0 PSI	-0.018V	-0.7m6V	11 <b>h</b> V	-50°F to 75°F	-3.6665ÆS	9.1411 <b>F</b> S
100 PSI	18.4 <b>6</b> V	19.5 <b>5</b> V	19.5mV	75°F to 150°F	9.3923 <b>F</b> S	-9.2918ES
Sensitivity	18.49V	20.3±V	18.4 <b>6</b> V	AVERAGE	0.0235%s	0.0232 <b>%</b> S

Pressure and Thermal Hysteresis											
TEMPERATURE (°F)	-50	-30	-10	10	30	50	70	90	110	130	150
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66
TEMP. SENSOR OUTPUT (mV)	-166.8	-140.2	-113.5	-86.4	-59.9	-33.6	-8.2	18.1	42.0	66.2	89.
PRESSURE SENSOR OUTPUT (mV)	-0.31	-0.15	0.00	0.15	0.27	0.41	0.55	0.74	0.85	0.85	0.8

MICRON INSTRUMENTS

PRESSUR	E TRANSDUCER CALIB	RATION DATA	12 Mar 2002
Model Number	Serial Number	Pressure Range	Type Unit
150584	60717	100PSI	Gage
Diaphragm Naterials	Customer	Excitation	Excitation Type
Steel	HUNTSVILLE	4.0nA	Constant Current

	Pr	Date of Pressure Calibration  6 Oct 99					
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%PS)
0 PSI G	-0.26	-0.344	-0.31-	-0.26°V		0.2356	0.235
20PSI G	4.02	3.987	4.00=V	4.04mV	0.0754%	0.1885	0.094
40PSI G	8.32∀	8.28v	8.27= ::	8.33 <sup>mV</sup>	0.0566%	0.18858	0.235
60PSI G	12.5 <b>6</b> %	12.59v	12.55	12.63mV	0.3205%	0.14148	0.047
80PSI G	16.92:	16.82v	16.92-	16.92mV	0.0189%		
100PSI G	21.22		21.22-	21.22mV	0.01898	0.4713	0.000
SENSITIVITY	21.48	L	21.22	21.22#		Ĺ	0.000

STATIC ERROR BAND

\* 0.2356 FS

		Thermal Cal	ibration Dat	a	Date of Thermal Cal	ibration
	Low Temp.	6 Oct 99				
Temperature	-50°F	50°F	150°F	Temperature Range	Thermal Balance Shift	Thermal Sensitivity Shift
0 PSI	-0.1%V	0.2 <b>6</b> V	-0.318V	-50°F to 50°F	1.6023 <b>F</b> S	-1.8850ES
100 PSI	21.3 <b>5</b> V	21.3 <b>0</b> V	20.9 <b>p</b> V	50°F to 150°F	-2.7333ES	0.8483 <b>F</b> S
Sensitivity	21.5£V	21.1 <b>6</b> V	21.2£V	AVERAGE	0.0068 <b>%</b> S	0.0047 <b>%</b> S

Pressure and Thermal Hysteresis												
TEMPERATURE (FF)	-50	-30	-10	10	30	50	70	90	110	130	150	
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66	
TEMP. SENSOP OUTPUT (EV)	-218.9	-175.1	-131.2	-86.5	-44.6	0.2	43.5	84.5	125.5	172.5	216.	
PRESSURE SENSOR OUTPUT (FV)	-0.08	-0.08	-0.09	-0.11	-0.15	-0.18	-0.16	-0.12	-0.31	-0.45	-0.6	

MICRON INSTRUMENTS

PRESSUI	RE TRANSDUCER CALIE	RANSDUCER CALIBRATION DATA					
Nodel Number	Serial Number	Pressure Range	Type Unit				
150584	60718	100PSI	Gage				
Diaphragm Materials	Customer	Excitation	Excitation Type				
Steel	HUNTSVILLE	4. 6nA	Constant Current				

	Pr	essure Cal	ibration Da	ta	Date of P.	Date of Pressure Calibration 29 Sep 99					
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%FS)				
0 PSI G	-0.30	-0.32√	-0.32°V	-0.30 <sup>nV</sup>		0.0928	0.0928%				
20PSI G	4.07	4.07°V	4.05=v	4.07mV	0.0093%	0.0000	0.0928%				
40PSI G	8.45	8.44v	8.43mv	8.44mV	0.0278%	0.04648	0.0928%				
60PSI G	12.8 <b>1</b> °	12.8 <b>2</b> v	12.80=v	12.82mV	0.0278%	0.04648	0.04648				
80PSI G	17.20:	17.20v	17.16 v	17.19 <sup>mV</sup>	0.0557%	0.00008	0.1855%				
100PSI G	21.56:		21.52-v	21.56mV			0.1855%				
SENSITIVITY	21.86	L				L					

STATIC ERROR BAND

± 0.0928 FS

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		Date of Thermal Calibration 29 Sep 99				
	Low Temp.	Ambient	High Temp	Temperature	Thermal	Thermal
Temperature	perature -50°F 50°F	150°F	Range	Balance Shift	Sensitivity Shift	
0 PSI	0.2 <b>2</b> nV	-0.1 <b>m</b> V	-0.1½V	-50°F to 50°P	-1.5306%S	1.1596 <b>F</b> S
100 PSI	21.0 <b>0</b> V	20.9 <b>2</b> V	20.6mV	50°F to 150°F	-0.0464ES	-1.3915ES
Sensitivity	20.7£V	21.0mkV	20.7∄V	AVERAGE :	0.0039\s	0.0035 <b>F</b> S

Pressure and Thermal Hysteresis												
TEMPERATURE (°F)	-50	-30	-10	10	30	50	70	90	110	130	150	
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66	
TEMP. SENSOR OUTPUT (mV)	-201.2	-150.2	-99.3	-48.5	2.0	52.2	101.7	155.1	203.6	251.1	297.	
PRESSURE SENSOR OUTPUT (mV)	0.31	0.16	0.04	-0.05	-0.10	-0.13	-0.10	-0.04	0.03	0.11	0.23	

MICRON INSTRUMENTS

PRESSURI	TRANSDUCER CALIE	RATION DATA	Date 12 Mar 2002
Nodel Number	Serial Number	Pressure Range	Type Unit
150584	60719	100PSI	Gage
Diaphragm Materials	Customer	Excitation	Excitation Type
Steel	HUNTSVILLE	4.6nA	Constant Current

	Pr	essure Cal	ibration Dat	a	Date of Pa	ressure Calibrat	ion
						25 Sep	99
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%PS)	Repeatability (%PS)
0 PSI G	0.03v	v€0.0	0.03=7	0.03mV		0.00008	0.000
20PSI G	3.89v	3.89v	3.88=*	3.89mV	0.0000%	0.0000	0.051
40PSI G	7.74	7.740	7.75-	7.75mV	0.0517%	0.00006	0.051
60PSI G	11.5 <del>9</del> v	11.59v	11.57-	11.61mV	0.1035%	0.00006	0.031
80PSI G	15.46v	15.45	15.44-	15.47mV	0.0517%	0.00008	
100PSI G	19.33v		19.30-v	19.33mv	0.031/18	0.05178	0.1035
SENSITIVITY	19.30	Ĺ	23.30	19.33.0			0.1552

\* 0.0776**\$**FS

		Thermal Cal	ibration Dat	a	Date of Thermal Cal	ibration	
	Low Temp.	Ambient	High Temp	25 Sep 99			
Temperature -5	-50°F	50°F	150°F	Temperature Range	Thermal Balance Shift	Thermal Sansitivity Shift	
0 PSI	0.4 <b>0</b> nV	0.3 mV	-0.25V	-507 to 50°F	-0.4656ES	-0.0517 <b>E</b> S	
100PSI	18.0 <b>0</b> V	17.9 <b>5</b> V	16.7 <b>3</b> V	50°F to 150°F	-2.8971ES	-3.1557ES	
Sensitivity	17.6£NV	17.5 <b>9</b> V	16.9£NV	AVERAGE	0.0084¥S	0.0080FS	

Pressure and Thermal Hysteresis												
TEMPERATURE (°F)	-50	-30	-10	10	30	50	70	90	110	130	150	
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66	
TEMP. SENSOR OUTPUT (EV)	-260.5	-199.€	-137.5	-75.2	-12.4	50.7	116.7	184.2	247.4	309.5	369	
PRESSURE SENSOR OUTPUT (mV)	0.28	0.04	-0.16	-0.32	-0.45	-0.53	-0.55	-0.57	-0.56	-0.51	-0.	

MICRON INSTRUMENTS

PRESSUR	E TRANSDUCER CALIB	TRANSDUCER CALIBRATION DATA					
Model Number	Serial Number	Pressure Range	Type Unit				
150584	60720	100PSI	Gage				
Diaphragm Materials	Customer	Excitation	Excitation Type				
Steel	HUNTSVILLE	4. CnA	Constant Current				

	Dr	eccure Cal	ibration Dat		Date of P.	ressure Calibrat.	ion
		cooure car	IDIACION DA	.a		25 Sep	99
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%FS)
0 PSI G	-0.04	-0.0¤\$v	-0.04v	-0.04 <sup>nV</sup>		0.0000%	0.0000
20PSI G	4.07	4.06v	4.06mV	4.05mV	0.0881%	0.0490%	0.049
40PSI G	8.17v	8.17v	8.16mv	8.14 <sup>mV</sup>	0.1273%	0.0000	0.049
60PSI G	12.2 <del>9</del> v	12.28v	12.28 v	12.24mV	0.2644%	0.04908	0.049
80PSI G	16.4 <del>2</del> v	16.42v	16.40mv	16.33mV	0.4505%	0.0000	0.097
100PSI G	20.4 <del>2</del> v		20.49=v	20.42mv			0.342
NSITIVITY	20.46v	_				L	

					±	0.2253 <b>\</b> S	
		Date of Thermal Cal	ibration Sep 99				
	Low Temp. Ambient High Temp Temperature		Thermal	Thermal			
Temperature	-50°F	50°F	150°F	Range	Balance Shift	Sensitivity Ship	
0 PSI	-0.43V	-0.1 <b>m</b> V	-0.0mgV	-50°F to 50°F	1.5671 <b>\</b> S	1.1263 <b>F</b> S	
100 PSI	18.53V	19.0 <b>%</b> V	18.7 <b>5</b> V	50°F to 150°F	0.0979 <b>F</b> S	-1.7140ES	
Sensitivity	18.9£6V	19.18V	18.8 <b>±</b> V	AVERAGE	0.0042\S	0.0043¥S	

Pressure and Thermal Hysteresis											
TEMPERATURE (°F)	-50	-30	-10	10	30	50	70	90	110	130	150
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66
TEMP. SENSOR OUTPUT (mV)	-257.9	-197.2	-134.9	-72.1	-8.6	55.6	122.5	190.9	255.1	319.0	382.6
PRESSURE SENSOR OUTPUT (mV)	-1.10	-0.97	-0.84	-0.72	-0.62	-0.55	-0.42	-0.41	-0.44	-0.44	-0.52

MICRON INSTRUMENTS

PRESSUR	E TRANSDUCER CALIB	TRANSDUCER CALIBRATION DATA						
Nodel Number	Serial Number	Pressure Range	12 Mar 2002					
150584	60721	100PSI	Gage					
Diaphragm Materials	Customer	Excitation	Excitation Type					
Steel	HUNTSVILLE	4.0nA	Constant Current					

	Pr	essure Cal	ibration Da	ta	Date of P	25 Sep	
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%FS)
0 PSI G	-0.06	-0.0 <del>:5</del> /	-0.05	-0.06°V		0.0476	0.0476
20PSI G	4.16 <sup>v</sup>	4.16	4.16**	4.15mV	0.03818	0.0000	0.0470
40PSI G	8.38v	8.37	8.36=	8.36mV	0.0762%	0.0000	0.0000
60PSI G	12.6av	12.60	12.58-				010352
80PSI G				12.58 <sup>mV</sup>	0.1619%	0.0476	0.1429
80PSI G	16.8€∨	16.81	16.80-	16.79 V	0.0571%	0.04768	0.0000
100PSI G	21.00:		21.01-7	21.00mv			
SENSITIVITY	21.06	L					0.0476

STATIC ERROR BAND

2 0.0810 FS

		Thermal Cal	ibration Dat	a	Date of Thermal Ca.	libration	
	Low Temp.	Thermal	Sep 99				
Temperature	-50°F	50°F	High Temp	Range		Thermal Sensitivity Shift	
0 PSI	-0.2m6V	-0.11 <b>5</b> V	0.0 <b>1</b> mV	-507 to 50°F	0.5238 <b>F</b> S	0.5714 <b>F</b> S	
100PSI	19.1 <b>m</b> V	19.3 <b>本</b> V	19.2 <b>8</b> V	50°F to 150°F	0.7619 <b>F</b> S	-1.0476ES	
Sensitivity	19.3fAV	19.4 <b>9</b> V	19.2ENV	AVERAGE	0.0032¥s	0.0026%5	

Pressure and Thermal Hysteresis												
TEMPERATURE ('F)	-50	-30	-10	10	30	50	70	90	110	130	150	
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66	
TEMP. SENSOR OUTPUT (mV)	-264.0	-205.0	-144.2	-83.0	-20.7	42.2	108.5	176.1	239.9	303.0	365	
PRESSURE SENSOR OUTPUT (mV)	-0.76	0.74	-0.72	-0.70	-0.67	-0.66	-0.61	-0.62	-0.64	-0.65	-0.0	

MICRON INSTRUMENTS

PRESSURE	PRESSURE TRANSDUCER CALIBRATION DATA							
Model Number	Serial Number	Fressure Range	23 Jul 2002					
150584	62180	100PSI	Gage					
Diaphragm Materials	Customer	Excitation	Excitation Type					
Steel	HUNTSVILLE	4. GnA	Constant Current					

	Pr	essure Cal	ibration Da	ta	Date of Pressure Calibration  5 Jul 01					
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%PS)			
0 PSI G	1.30v	1.29v	1.29=1	1.30mV		0.05148	0.0514			
20PSI G	4.96v	4.90v	4.89=:	4.93mV	0.1644%	0.00008	0.0514			
40PSI G	8.53v	8.53v	8.52=:	8.56 <sup>mV</sup>	0.17478	0.00008	0.0514			
60PSI G	12.19	12.1₹v	12.16	12.20mV	0.0308%	0.1028	0.1542			
80PSI G	15.80	15.8±v	15.78	15.83mV	0.1439%	0.05148	0.1028			
100PSI G	19.46v		19.47-1	19.46mV		3.03146				
SENSITIVITY	18.16v	L				L	0.0514			

\* 0.0874%FS

		Thermal Cal	ibration Dat	a		Date of Thermal Cal	
	Low Temp.	Ambient	High Temp	Tamperature Range		Thermal	Aug 99
Temperature	-50°F	50°F	150°F			Balance Shift	Thermal Sensitivity Shift
0 PSI	2.2 <b>t</b> nV	0.6 <b>2</b> 7V	-2.219V	-50F to	50°F	-8.3248ES	0.1028 <b>F</b> S
100 PSI	20.41bV	18.8mV	15.2 <b>5</b> V	50°F to	150°F	-14.9538ES	-3.3402ES
Sensitivity	18.15NV	18.1 <del>9</del> V	17.5 <b>≙</b> V	AVERAGE	1	0.0582%s	0.0084%S

			Pr	essure	and Th	ermal 1	lystere	sis			
TEMPERATURE (°F)	-50	-30	-10	10	30	50	70	90	110	130	150
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66
TEMP. SENSOR OUTPUT (mV)	-182.9	-136.3	-88.1	-40.0	7.7	51.9	103.8	158.7	204.2	251.3	302
PRESSURE SENSOR OUTPUT (mV)	3.98	3.44	2.93	2.49	2.10	1.71	1.34	1.30	0.84	-0.73	-1.

MICRON INSTRUMENTS

PRESSUR	RE TRANSDUCER CALIB	RATION DATA	Date - 23 Jul 2002
Nodel Number	Serial Number	Pressure Range	Type Unit
150584	62181	100PSI	Gage
Diaphragm Materials	Customer	Excitation	Excitation Type
Steel	HUNTSVILLE	4.0nA	Constant Current

	Pr	essure Cal	ibration Da	ta	pate of Pressure Calibration 5 Jul 01					
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%PS)	Repestability (%F5)			
0 PSI G	0.96v	0.95∨	0.95-	0.96™∨		0.0396	0.0396			
20PSI G	5.78v	5.77∵	5.78-*	5.82 <sup>mV</sup>	0.1505%	0.0396	0.0000			
40PSI G	10.6 <b>6</b> :	10.6 <b>1</b> v	10.64-	10.68mV	0.0634%	0.1980	0.0792			
60PSI G	15.48	15.45v	15.50-v	15.53mV	0.2139%	0.1188	0.0792			
80PSI G	20.36	20.27	20.35	20.39mV	0.1267%	0.3564	0.0396			
100PSI G	25.25		25.21-1	25.25mV			0.1584			
SENSITIVITY	24.29:	L				L				

STATIC ERROR BAND

\* 0.1782\FS

		Date of Thermal Calibration  8 Oct 99				
	Low Temp.	Ambient	High Temp	Temperature	Thermal	Thermal
Temperature	mperature -50°F 50°F	150°F	Range	Balance Shift	Sensitivity Shift	
0 PSI	0 PSI -0.756V -0.25V	0.8 <b>T</b> NV	-50°F to 50°F	2.0990 <b>F</b> S	-1.7426ES	
100 PSI	23.8mV	23.9 <b>\$</b> V	23.1 <b>9</b> V	50°F to 150°F	4.3564 <b>F</b> S	-7.4059ES
Sensitivity	24.6±V	24.1 <del>9</del> V	22.3£V	AVERAGE	0.0161\FS	0.0229¥s

Pressure and Thermal Hysteresis												
TEMPERATURE (FF)	-50	-30	-10	10	30	50	70	90	110	130	150	
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66	
TEMP. SENSOR OUTPUT (RV)	-102.6	-76.3	-49.1	-21.9	6.1	33.9	62.4	95.1	122.7	151.3	179.	
PRESSURE SENSOR	-0.99	-0.92	-0.83	-0.70	-0.58	-0.41	-0.18	0.14	0.28	-0.27	0.38	

### MICRON INSTRUMENTS

PRESSURE	TRANSDUCER CALIBR	ATION DATA	Date - 23 Jul 2002
Nodel Number	Serial Number	Pressure Range	Type Unit
150584	62176	100PSI	Gage
Diaphragm Materials	Customer	Excitation	Excitation Type
Steel	HUNTSVILLE	4.0nA	Constant Current

	Pr	essure Cal	ibration Da	ta	Date of P	ressure Calibrat 5 Jul	
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%FS)
0 PSI G	0.22v	0.22°v	0.22 ***	0.22mV		0.0000\$	0.0000
20PSI G	4.37v	4.36v	4.37mV	4.40mV	0.1232%	0.04748	0.0000
40PSI G	8.53v	8.5±v	8.52mv	8.57mV	0.1991%	0.09486	0.0474
60PSI G	12.70	12.70v	12.70=1	12.75mV	0.2275%	0.00008	0.0000
80PSI G	16.85°	16.82v	16.89=v	16.92mV	0.3507%	0.14228	0.1896
100PSI G	21.10		21.07mV	21.10mV			0.1422
SENSITIVITY	20.8€√					L	

static error band ± 0.1754%S

_		Date of Thermal Calibration  8 Oct 99				
	Low Temp.	Ambient	High Temp	Temperature	Thermal	Thermal
Temperature	-50°F	50°F	150°F	Range	Balance Shift	Sensitivity Shift
0 PSI	1.9 <b>t</b> nV	0.4 <b>0</b> V	0.3 <b>6</b> 1V	-50°F to 50°F	-7.2512\S	0.2844 <b>\</b> S
100 PSI	22.7 <b>8</b> V	21.3mV	21.4 <b>3</b> V	50°F to 150°F	-0.4739ES	1.0427 <b>F</b> S
Sensitivity	20.85aV	20.9mV	21.1mkV	AVERAGE	0.0193%rs	0.0033 <b>%</b> S

Pressure and Thermal Hysteresis											
TEMPÉRATURE (°F)	-50	-30	-10	10	30	50	. 70	90	110	130	150
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66
TEMP. SENSOR OUTPUT (mV)	-81.2	-61.6	-41.2	-20.5	0.8	21.7	43.3	69.0	91.0	113.8	138.
PRESSURE SENSOR OUTPUT (mV)	2.02	1.65	1.30	1.02	0.75	0.56	0.43	0.51	0.52	0.19	0.19

MICRON INSTRUMENTS

	PRESSURE TRANSDUCER CALIBRATION DATA							
Model Number	Serial Number	Pressure Range	23 Jul 2002					
150584	62177	100PSI	Gage					
Diaphragm Materials	Customer	Excitation	Excitation Type					
Steel	HUNTSVILLE	4. CnA	Constant Current					

	Pr	essure Cal	ibration Dat	ta	Date of P.	ressure Calibrat	ion			
					27 Sep 99					
Pressure	Increase (1)	Decrease	Increase(2)	Streight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%75)			
0 PSI G	0.24	0.21v	0.21=7	0.24mV		0.1333	0.133			
20PSI G	4.64V	4.65	4.64=	4.69**	0.2311%	0.0444				
40PSI G	9.070	9.04	9.07#*	9.14**	0.3289%	0.13336				
60PSI G	13.45v	13.48v	13.52-v	13.60 <sup>mV</sup>	0.64898	0.13336	0.311			
80PSI G	18.00v	17.88v	18.00-	18.05mV	0.2133%	0.5333				
100PSI G	22.50v		22.41-1	22.50=v	0.21330	0.33336	0.000			
SENSITIVITY	22.26v	L		22.30		L	0.400			

STATIC ERROR BAND

2 0.3244 FS

			Pate of Thermal Calibration  27 Sep 99			
	Low Temp.	Ambient	High Temp	Temperature	Thermal	
Temperature	-50°F	50°F	150°F	Range	Balance Shift	Thermal Sensitivity Shift
O PSI	0.1 <b>0</b> V	0.1mV	-0.3m6V	-507 to 50°7	0.0444FS	-2.9778 <b>E</b> S
100PSI	23.0thV	22.3 <b>5</b> V	21.5 <b>8</b> V	50°F to 150°F	-2.0889ES	-1.3333ES
Sensitivity	22.9赴V	22.2 <b>±</b> V	21.9 <b>±</b> V	AVERAGE	0.0052%S	0.0108¥S

Pressure and Thermal Hysteresis												
TEMPERATURE (SF)	-50	-30	-10	10	30	50	70	90	110	130	150	
TEMPERATURE (FC)	-46	-34	-23	-12	-1	10	21	32	43	54	66	
TEMP. SENSOR OUTPUT (EV)	-136.8	-104.0	-70.8	-37.9	-4.7	27.8	60.9	98.1	130.9	164.1	196.	
PRESSURE SENSOR OUTPUT (EV)	0.82	0.56	0.33	0.17	0.01	-0.07	-0.11	-0.05	-0.02	-0.13	-0.0	

### MICRON INSTRUMENTS

PRESSURE	TRANSDUCER CALIB	Date - 23 Jul 2002	
Model Number	Serial Number	Pressure Range	Type Unit
150584	62178	100PSI	Gage
Diaphragm Materials	Customer	Excitation	Excitation Type
Steel	HUNTSVILLE	4.0nA	Constant Current

	Pr	essure Cal	ibration Da	ta	Date of P.	ressure Calibrat	
		_	Linearity	27 Sep	99 Repeatability		
Pressure	Increase (1)	Decrease	Increase(2)	through Endpoints	(%FS)	(%FS)	(%PS)
0 PSI G	-0.69'	-0.69v	-0.69∵	-0.69°V		0.00008	0.0000
20PSI G	3.6±v	3.61°	3.60mV	3.61 <sup>mV</sup>	0.0096%	0.0000	0.0480
40PSI G	7.9±v	7.9±v	7.93mv	7.91 <sup>mV</sup>	0.0192%	0.0000s	0.0961
60PSI G	12.2€	12.20v	12.29≂∵	12.22mV	0.0192%	0.09618	0.3362
80PSI G	16.60	16.47v	16.55≂∵	16.52mV	0.3939%	0.6244	0.2402
100PSI G	20.8⊋√		20.97±v	20.82mv			0.7205
SENSITIVITY	21.5av					_	

static error band

± 0.3602%FS

		Thermal Cal	ibration Dat	a	Date of Thermal Cal	ibration Sep 99
	Low Temp.	Ambient	High Temp	Temperature	Thermal	Thermal
Temperature	-50°F	50°F	150°F	Range	Balance Shift	Sensitivity Shift
G PSI	-7.8 <b>5</b> V	-1.2 <b>5</b> V	-1.3 <b>2</b> V	-50°F to 50°F	31.7963₹S	-27.8098 <b>%</b> S
100 PSI	19.4mV	20.310V	20.0mV	50°F to 150°F	-0.4323ES	-0.6724ES
Sensitivity	27.3£V	21.5av	21.3£NV	AVERAGE	0.0795%s	0.0712¥FS

			Pr	essure	and Th	ermal H	ysteres	sis			
TEMPERATURE (°F)	-50	-30	-10	10	30	50	70	90	110	130	150
TEMPERATURE (°C)	-46	-34	-23	-12	-1	10	21	32	43	54	66
TEMP. SENSOR OUTPUT (mV)	-73.5	-55.2	-36.6	-18.2	0.5	18.8	37.3	58.1	76.5	95.0	113.
PRESSURE SENSOR OUTPUT (mV)	-1.85	-1.80	-1.71	-1.61	-1.48	-1.35	-1.12	-0.82	-0.76	-0.74	-0.5

MICRON INSTRUMENTS

	E TRANSDUCER CALIB	RATION DATA	Date 23 Jul 2002
Nodel Number	Serial Number	Pressure Range	Type Unit
150583	62179	100PSI	Gage
Diaphragm Materials	Customer	Excitation	Excitation Type
Titanium	HUNTSVILLE	4. mA	Constant Current

	Pr	essure Cal	ibration Da	ta	Date of Pr	6 Jul	
Pressure	Increase (1)	Decrease	Increase(2)	Straight Line through Endpoints	Linearity (%FS)	Hysteresis (%FS)	Repeatability (%7S)
0 PSI G	0.75	0.64v	0.64=v	0.75mV		0.30528	0.3052
20PSI G	7.76v	7.63	7.63=	7.815	0.1332	0.36076	0.3607
40PSI G	14.86	14.7av	14.72	14.87mV	0.18318	0.2497	0.3007
60PSI G	21.8≅v	21.78	21.72-1	21.92**	0.1498%	0.24978	0.4162
80 PSI G	28.98/	28.88v	28.81-7	28.98mV	0.0055%	0.2775	0.4717
100PSI G	36.04v		35.98-	36.04=v	2.00340	0.27736	
SENSITIVITY	35.2 <del>9</del> v	L		55.03			0.1665

STATIC ERROR BAND

0.2358**F**S

		Thermal Cal	ibration Dat	a	Date of Thermal Cal		
	Low Temp.	Ambient	High Temp	Temperature	Thermal	Jul 01	
Temperature	-50°F	50°F	150°F	Range	Balance Shift	Thermal Sensitivity Shift	
0 PSI	0.5 <b>0</b> v	-0.0m6V	-0.90%	-507 to 50°F	-1.5538ES	0.2497 <b>F</b> S	
100PSI	35.7 <b>0</b> V	35.2 <b>3</b> V	34.6 <b>p</b> V	50°F to 150°F	-2.3307ES	0.5827 <b>F</b> S	
Sensitivity	35.2£0V	35.29V	35.5£N	AVERAGE	0.0097¥s	0.0021%s	

			Pr	essure	and Th	ermal H	ysteres	is			
TEMPERATURE (FF)	-50	-30	-10	10	30	50	70	90	110	130	150
TEMPERATURE +°C/	-46	-34	-23	-12	-1	10	21	32	43	54	66
TEMP. SENSOR OUTPUT (EV)	-420.9	-355.7	-288.6	-221.8	-153.8	-87.5	-20.7	58.3	123.3	164.0	250
PRESSURE SENSOR	0.50	0.40	0.29	0.18	0.06	-0.06	-0.16	-0.22	-0.30	-0.51	-0.

MICRON INSTRUMENTS

## APPENDIX B

## LOGGER CALIBRATION SHEETS

## Data Logger Calibration Report Serial # 9823-0006

No.	ML-1001- 8	Quiescent > Power:	=75	Remote Start	ОК
Serial No.	9823-0006	Header	OK	0.011	
SGC S/N:	9823-0006	Memory: Data	ОК		
Date: Temp (C)	4/2/02 25	Memory: Download: Low Battery:	OK OK		

	Iexc-uA	Voffset	Max Dev	3-Sigma	Vin	Vout	MaxDev	3-Sigma	Gain	Gain
ChNo.	MicroAmp s	Milli-Volts	Counts	Counts	MilliVolts	Milli-Volts	Counts	Counts	Vout/Vin	Error Percent
1	1023.44	2,033.48			11.1852	3,821.43		1.5	159.850	-0.09%
2	1023.44	1,296.02			63.2284	2,558.32		0.39	19.964	-0.18%
3	784.69	2,041.04			10.8631	3,757.71		0.58	158.028	-1.23%
4	784.69	1,020.00			61.4031	2,232.17		0	19.741	-1.29%
5	781.53	2,041.37			10.8555	3,756.76		1.44	158.020	-1.24%
6	781.53	1,020.31			61.3602	2,233.41		1.38	19.770	-1.15%
7	783.75	2,043.01			10.8787	3,762.41		0.29	158.052	-1.22%
8	783.75	1,020.59			61.493	2,235.49		1.49	19.757	-1.22%

NOTES: Data in BOLD face is to be entered in the DataLogger software Calibration

Measurements taken from the data logger are based on 100 or more sequential readings at 1/2 second

Iexc and Vin measurements were taken with an HP 34970A Data Acquisition Unit. Readings were integrated over 100 line

April 02,2002: changed fixed gain on temperature channels to 20 nominal.

## **Data Logger Calibration Report** Serial # 0107-0004

Model No. Serial No. SGC S/N:

ML-1008-1 0107-0004 9821-0033 Quiescent Power: >=73

Header Memory: OK Data Memory: OK

Download:

Remote Start

OK

Date: 4/4/02 Temp (C)

OK Low Battery: OK

ChNo.	lexc-uA MicroAmps	Voffset Milli-Volts	Max Dev Counts	3-Sigma Counts	<b>Vin</b> Milli∀olts	<b>Vout</b> Milli-Volts	MaxDev Counts	3-Sigma Counts	<b>Gain</b> Vout∕Vin	Gain Error
1	1017.75	2,044.00	0	0.00	11.1111	3,747.78	4	2.41	153.340	-4.16%
2	1017.75	1,322.00	0	0.00	62.8007	2,541.69	7	4.36	19.422	-2.89%
3	1017.93	2,037.00	. 0	0.00	11.1135	3,739.54	2	1.6	153.196	-4.25%
4	1017.93	1,320.00	1	1.00	62.8144	2,541.52	8	5.96	19.446	-2.77%
5	1017.7	2,041.23	1	1.00	11.1109	3,743.63	7	6.64	153.219	-4.24%
6	1017.7	1,321.70	1	1.00	62.7983	2,539.91	17	16.46	19.399	-3.01%
7	1017.5	2,044.00	0	0.00	11.109	3,747.24	2	1.77	153.321	-4.17%
8	1017.5	1,321.00	0	0.00	62.7891	2,541.57	7	6.18	19.439	-2.80%

NOTES:

Data in BOLD face is to be entered in the DataLogger software Calibration window.

Measurements taken from the data logger are based on 100 or more sequential readings at 1/2 second intervals.

lexc and Vin measurements were taken with an HP 34970A Data Acquisition Unit. Readings were integrated over 100 line cycles.

New board set with SN 9821-0033 installed into case 0107-0004 on April 04, 2002

Ву:

### Data Logger Calibration Report Serial #: 0207-001

Model No.	ML100	8-1HF			Quiescent Power:	N/A					
Serial No.	0207-0001				Header Memory:	OK			r Count ection	Nomin	al Gains
SGC S/N:	see below				Data Memory:	OK		mV	5000	Temperatu re	5.032
Date:	7/15/02				Download:	OK		Count	4096	Pressure	73.866
Temp (C)	25				Low Battery:	N/A		Ratio	1.220703	,	
					Remote Start	OK					
	lexc-uA	Voffset		Max Dev	3-Sigma	Vin	Vout	MaxDev	3-Sigma	Gain	Gain Error
ChNo./ Serial No.	MicroAmps	Counts	mV	Counts	Counts	MilliVolts	Counts	Counts	Counts	Vout/Vin	Percent
1 sn 0207-001a	4098.25	2,043.21	2494.15	13	7.90	321.506	3.364.58	316	57.9	5.017	-0.30%
2 sn 0207-001b	4098.25	2,044.95	2496.28	11	7.30	21.438	3.345.98	43	11.4	74.082	0.29%
3 sn 0207-002a	4098.73	2,045.99	2497.55	13	6.80	321.456	3,364.78	288	53.3	5.008	-0.48%
4 sn 0207-002b	4098.73	2,043.72	2494.77	13	8.20	21.428	3,343.50	49	11.5	74.045	0.24%
5 sn 0207-003a	4096.34	2,046.74	2498.46	14	10.20	321.424	3,365.68	324	55.4	5.009	-0.46%
6 sn 0207-003b	4096.34	2,046.14	2497.73	12	10.40	21.433	3,344.31	41	12.9	73.936	0.10%
7 sn 0207-004a	4098.80	2,046.41	2498.06	14	8.50	321.645	3,366.20	313	55.4	5.009	-0.46%
8 sn 0207-004b	4098.80	2,043.63	2494.67	12	8.10	21.448	3,348.03	46	13.8	74.239	0.51%
	Calibration w	indow.			gger software		Data in Yello		ed.		
	Please note t	hat for this v	ersion of the	HF logger,	Voffset is give	n in both C	ounts and m\	/.			
	Measuremen	ts taken from	n the data lo	gger are bas	ed on 100 or	more seque	ential readings	s at approxin	nately 1/10 s	econd interva	als.
	lexc and Vin	measureme	ents were tak	en with an H	IP 34970A Da	ta Acquisiti	on Unit. Rea	dings were ir	ntegrated ove	er 100 line cy	cles.
By:											
Бу.											
	WKBorsum										
			]								

### **APPENDIX C**

### Sensor Related Papers:

- a) Improvements in rocket motor life instrumentation. E C Francis et al, JANNF S&MB Meeting (Dec 1995)
- Stress Measurement in Solid Rocket Motors.
   H J Buswell, 18<sup>th</sup> Transducer Workshop, RCC (June 1995)
- c) Service Life Prediction Methodologies. Final Reports TTCP KTA 4-14 (1996)
- d) Miniature sensor for measuring solid grain rocket motor case bond stress. H Chelner et al, Paper 25 AGARD Conference Proceedings 586 (May 1997)
- c) Service Life Prediction Using Stress Gage Technology and Nonlinear viscoelastic analysis. F C Wong, Paper 26 AGARD Conference Proceedings 586 (May 1997)
- e) Instrumented Service Life Programme for the Pictor Rocket Motor. S Y Ho, Paper 28 AGARD Conference Proceedings 586 (May 1997)
- f) Bond Line Stress Transducers Effectiveness in Measuring Crack Formation in Solid Propellant Analog Motors.
   R W Pritchard, JANNAF JPM (1998)
- g) Failure Analysis of Rocket Motors on Pressurization Final Reports TTCP KTA 4-23 (1999)
- h) Characterisation and Use of Bond Stress Sensors in Tactical Rocket Motors. H J Buswell, AIAA Paper #2000-3139 JPC (2000)

## APPENDIX D

## Gage Matching Test Data

cł	R Plus Current	R Neg Current R	Average	ACTUAL	
0	105.65651037453	3 105.6578340101	105.65717219232	105.50	
1	498.56448697249		498.56470233646	105.59	
2	496.342754157	496.31695266045		498.54	
3	499.64495437767	499.61848832243		496.34	
4	498.13890093668	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		499.62	
5	498.80941607881			498.19	
6	497.58824471893			498.82	AMERICA
7	496.48693228342			497.67	AVERAGE 497.92
8	497.51702419865			496.57	ALIERAGE
9	498.13542676496			497.63	AVERAGE DIFFERENCE 0.07
10	498.22054397212			498.25	
11				498.33	
12				498.30	
13	105.48934926596	105.51219572534		497.06 105.51	
14				100.09	
		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	100.05051740002	100.09	
ch	R Plus Current	R Neg Current R	Average		
0	105.66326270054	105.64035066234	105.65180668144		
1	498.55064410212	498.53712782043	498.54388596128		
2	496.32030332771	496.29963306528	496.30996819649		
3	499.62412587672	499.59589573488	499.6100108058		
4	498.14418012922	498.09901695928	498.12159854425		
5	498.80946090539	498.73010522356	498.76978306447		
6	497.57790980799	497.54790131252	497.56290556025		
7	496.46621347183	496.44393148383	496.45507247783		
8	497.51885094013	497.46966723017	497.49425908515		
9	498.11465069529	498.0885857483	498.1016182218		
	498.20323899708	498.17029690098	498.18676794903		
11	498.1771836142	498.15291154935	498.16504758177		
12	496.96126574653	496.90812037243	496.93469305948		
13	105.49704271951	105.50594852087	105.50149562019		
14	100.09088481556	100.09094642111	100.09091561833		
^	105 (5)				
	105.65408834299		105.6406473108		
	498.52472550649	,498.4557024775	498.490213992		
	496.28763088565	496.23076420448	496.25919754507		
	499.59637719986	499.51950108929	499.55793914457		
	498.08529620597	498.01940598803	498.052351097		
	498.75746671704	498.63821694521	498.69784183113		
	497.53470692428	497.48055375003	497.50763033716		
	496.42137023798	496.36113168142	496.3912509597		
	497.46523193606	497.38147446756	497.42335320181		
	498.0644537095	498.00897658987	498.03671514969		
	498.14782369537	498.09067354209	498.11924861873		
	498.13392869772	498.05938534762	498.09665702267		
	496.89901078203	496.8182869672	496.85864887461		
	105.48146971841	105.4888161877	105.48514295305		
14	100.09087866089	100.09093409143	100.09090637616		

SENSOR AND LOGGER DATA SHEETS

## **Dual Temperature and Normal Bond Stress Transducer**

P/N 140583 6AL4V Titanium P/N 140584 17-4 CRES

his dual output miniature semiconductor pressure sensor has been optimized for normal bond stress and temperature measurements in solid grain rocket motors. A silicon high response stress insensitive temperature sensor has been bonded to the diaphragm.

The sensor can be left in place in order to measure chamber pressure.

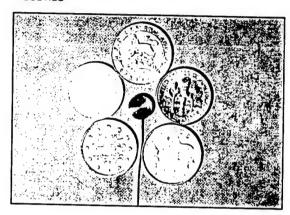
The cable can be removed from the remote bridge completion box. Water seals and individual screw terminal blocks permit easy removal of the Teflon® covered cable, which is circular and has a diameter of 0.055" max.

The sensor is recalibrated to provide positive signal for compressive forces. Excitation to the sensor is 4.0 mA constant current which corrects for line resistance changes due to temperature effects or poor connections. Other current levels or constant voltage excitation are available; consult the factory for these options.

Thermal hysteresis data is an option. Data is presented every 20°F between -50°F and +150°F for three cycles. The stress sensor balance output and temperature sensor outputs are depicted graphically over these temperatures.

### **Applications**

- SOLID GRAIN ROCKET MOTORS
- BOND STRESS MEASUREMENTS
- HIGH FREQUENCY CHAMBER PRESSURES
- PRODUCTION EQUIPMENT AND CONTROLS
- ROBOTICS



#### Mechanical

Standard Stress Range ..... ±100 psig (7.03 kg/cm²)

Non Standard Pressure Ranges ...... Consult Factory

Over Pressure (No change in performance) ..... 2.0x Range

Usable Pressure (Small change in balance) ..... 10.0x Range

Maximum Over Range with 50% Zero Shift ..... 20x Range [140583 [6AL4V Titanium]]

30x Range (140584 [17-4 PH CRES Steel])

### Performance (Stress)

Balance (Zero) Output	0.0 ± 1.0 mV		
Full Scale Sensitivity	45 ± 10 mV (140583 [6AL4V Titanium] 25 ± 10 mV (140584 [17-4 PH CRES])		
Static Error Band	± 0.25% FS Max.  < ± 1.0 psi, -45° C to 66° C (-50° F to 150° F)  < 2.0% FS/year		
Thermal Hysteresis			
Long Term Stability			

### Performance (Temperature)

> 4509 Runway Street Simi Valley, Ca. 93063 Phone: (805) 522-4676 FAX: (805) 522-4982





## Micron Series Data Logger

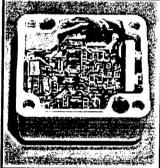
#### **GENERAL**

icron's Data Logger is designed to provide a versatile instrument for conditioning and storing signals under a wide variety of conditions. It uses a building-block architecture that allows the logger to be configured to meet the exact needs of high volume users, as well as providing a variety of off-the-shelf configurations.

The Data Logger is contained in an aluminum or plastic NEMA-4 container. A Serial Interface Adapter (SIA) provides the interface between the Data Logger and the host computer.

The Data Logger records from one to eight channels of information from connected sensors. Sampling rate, start and stop times are user definable from once per second to once every 18.2 hours. The Data Logger operates from a self contained 9 volt battery and is totally autonomous once the Data Logger setup information has been uploaded to memory.





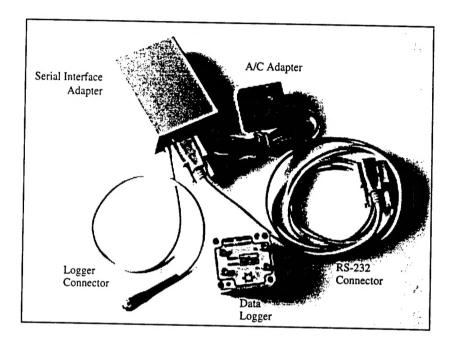
#### **FEATURES**

- 1 to 8 active channels, 12-bit resolution, minimal data skew.
- Non-volatile memory will survive complete power loss without losing data.
- Typical power consumption is 350 mAH per year of operation.
- Logging intervals from 1 second to 18 hours.
- Delayed start option to 194 days with 1 second increments.
- Local battery (9V transistor radio style) or external power inputs (7-15 VDC).
- 8 channels total, configured in four pairs.
- Constant voltage or constant current Excitation supplies for each pair of channels.
- Fixed gains and offset voltages correctable in software.
- Windows 95 (NT and CE available soon).
- Complete setup and download functions. Data is stored as a memory image, and in standard "Comma Separated Variable" format compatible with all spread-sheets and data bases.
- All calibration and test identification is stored in non-volatile logger memory.
- Multiple level access via passwords.
- "Real time" utility for displaying current measurements—used for checking logger operations for calibration of sensors.

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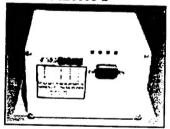


### MC1008-1



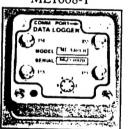
Constsnt Voltage Excitation 8 channels at 12 bits, memory to 81,920 samples, 1 sec to 18 hrs. pgrscan. It is a dedicated data logger set up internally for specific sensors. Although it can be adapted for most sensor types. Very low power consumption, up to 1 year off of 1 internal battery.

#### ML1008-2



Passive Backplane Logger
Designed for flexibility and will
accept a wide variety of plugh-in
signal conditioners and logger engines. It has 8 channels at 12 bit
resolution, memory to 114,688
samples, 1 scan/sec to 1 scan/18
hrs.

### ML1008-1



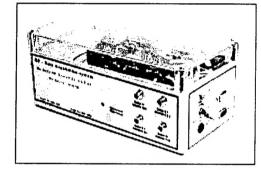
Constsnt Current Excitation 8 channels at 12 bits, memory to 81,920 samples, 1 sec to 18 hrs. pgrscan. It is a dedicated data logger set up internally for specific sensors. Although it can be adapted for most sensor types. Very low power consumption, up to 1 year off of 1 internal battery.

### High Frequency Data Logger

icron's HF1 logger is a microprocessor based, self contained data logger that can be customized for a wide vanety of applications. Included in a typical configuration are multiple signal conditioners, high speed and nonvulutile memory, a precision high-speed Analog to Digital converter, and a microprocessor controller. Although intended for high volume OEM applications, the unit is versatile enough to serve as a general purpose data logger, and can be set up to accept virtually any type of sensor. The logger and resident signal conditioners store at setup information. including sensor calibration factors on board in nonvolatile memory. Calibration information travels with the sensor/signal conditioner, allowing plug-and-play changing of sensors.

#### Applications

- Health Manitoring
- Seismic Monitoring
- Crash Testing
- Environmental Monitoring
- Flight Testing
- Transportation Shock recording



High sample rates, from 20 to 500 000 samples per second on 8 or 16 channels.

High Accuracy, 12 or 16-bit resolution

for 2 milion samples of event data in high speed mode

Pre- and Post-trigger data acquistion

Programmable exceedance level event triggers on each channel

Multiple trigger sources including exceedance, real time clock, or external switch obsure

Highly configurable signal condenders with non-volative memory for disipose or information.

Standard flash cards for nonvolatile data storage to several hundred megapytes.

Provered from internal patteries, external power sources, or both

#### Mechanical

The printed circuit deares comprising the typical legger stack can be configured to fit within a wide variety Fig. processings, resigning from topolar (approx 3.5) diameter by 51 ding) depade of wanetanding high-G shock and vibration, through simple polycarbonate NEMM-4 plastic enclosures for bench-top testing. The board stack is modifian, and can be reportly reconfigured to meeting changing regarements

#### Performance

Very high speed storage of data to along hufter at rates up to 500,000 samples per second. 15 or 15 bit resolution

Precision voltage references and evolution supplies

Precision instrumentation amplifiers.

Real Time Clock with drystal temperature compensated to approximately 5 min. /ym over the range of 0-50 degC

#### Environmental

As an optorithe ML-100x-HF may be adacted to most operating environments, it may be water proflectshock resistant to over 1000Gs, explained proof, and random frequency up to 162/Hz to 1000Hz.

#### Electrical

External power required is a scores of relatively clean power at 5 to 24 lights DC,

Active current: <200 mA plus excitation supply and signal conditioning requirements.

Sleep mode power +50 uA

Capable or providing constant votage or constant current excitation, and variants can also support 4-20 mA current loop sensors at 12, 18, or 24 vots loop compliance votage Communication, RS232 or RS485 motodrop, Other protocols available.

Runway Street FAX: (805) 522-4982

